

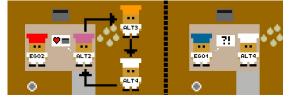
PantheonRL: A MARL Library for Dynamic Training Interactions

Bidipta Sarkar, Aditi Talati, Andy Shih, Dorsa Sadigh



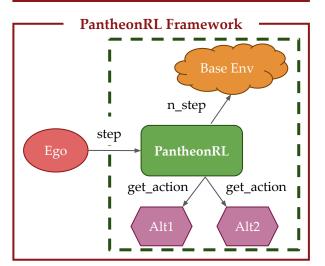
Overview

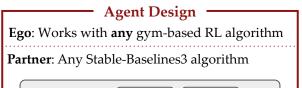
Supports Complex Training Interactions with existing single-agent RL algorithms



Round-Robin

Cross-Play





PPO

DQN

A2C

SAC

StaticPolicyAgent ActorCriticPolicy Can create custom partners with hard-coded get action and update

Example Scripts

Round-Robin Training

OnPolicyAgent

OffPolicyAgent

env = gym.make('0vercookedMultiEnv-v0', layout_name='simple'
partner_1 = PP0.load(partner_1_file)
env.add_partner_agent(StaticPolicyAgent(partner_1))
partner_2 = A2C('MlpPolicy', env)
env.add_partner_agent(OnPolicyAgent(partner_2))
ego = PP0('MlpPolicy', env, verbose=1)
ego.learn(total_timesteps=10000)

Ad-hoc Adaptation

env = gym.make('OvercookedMultiEnv-v0', layout_name='simple')
env.add_partner_agent(StaticPolicyAgent(partner_2.policy))
ego_b = PP0.load(ego_b_file, env=env)
ego_b.learn(total_timesteps=500000)

Web Interface

Allows for asynchron	ous trainin	g and
monitoring		
Partner Agent 2 (Optional)	PantheonRL	
You have successfully set 1 partner agent(s).		
Filling out this form again will add an additional partner.		
Pick a type of agent:	rollout/ep_len_mean:	400.0
PPO	rollout/ep_rew_mean:	0.0
Select	time/fps:	268.0
	train/approx_kk	0.010521722957491875
	train/clip_fraction:	0.08603515475988388
PPO Parameters	train/clip_range:	0.2000000298023224
Seed for randomness (optional):	train/entropy_loss:	-17835129499435425
23	train/explained_variance:	-0.6773374652862549
	train/licarning_rate:	0.010300000142492354
Save as: (if left blank, the trained ego policy will not be saved)	train,floss:	-0.04146458953619003
	train/policy_gradient_loss:	-0.015984073884785175
partnerb	train/walue_loss:	0.017384588718414307
Save Partner Agent	Check for Updates Create Tensorboard	

Use Cases

Decentralized MARL Training Human-AI Interaction Independent AI Collaboration



